1	ELECTRIC MOTOR WITH NONMOTOR DRIVING MEANS (E.G., AXLE	568.13	With particular program teaching method
	DRIVE, MANUAL DRIVE)	568.14	Manual lead through
2	.Manual driving means	568.15	With particular interpolation
3	WITH PARTICULAR MOTOR-DRIVEN LOAD		means
J	DEVICE	568.16	With particular sensing
4	.Plural, diverse or diversely		device
-	controlled load device	568.17	With multimode control (e.g.,
5	Plural motor drive		course-fine, position-force,
6	.Tension-maintaining type of		etc.)
O	motor-control system	568.18	Including velocity control
7	Plural, diverse or diversely	568.19	With particular coordinate
1	controlled motors		transformation means
8	.Plural, diverse or diversely	568.2	With plural control systems
O	controlled driving motors		(e.g., the interaction of
	(e.g., driving differential		plural processors to control
	gearing)		the plural joints of a single
9	.Power- or motion-transmitting		robot):
)	mechanism	568.21	Including end effector
10	Reversible drive mechanism		(e.g., gripping jaw,
11			micromanipulator, etc.)
12	Variable speed mechanism	568.22	With particular compensation
	Gearing		(e.g., gain, offset, etc.)
13	Differential type	568.23	Including program
14	Motion-converting mechanism		modification
15	Mechanical gearing	568.24	With reliability enhancement
16	SUPPLIED OR CONTROLLED BY SPACE-		means (e.g., monitoring,
	TRANSMITTED ELECTROMAGNETIC OR		redundant circuits, etc.)
	ELECTROSTATIC ENERGY (E.G., BY	568.25	Including display device
1 7	RADIO)	569	Digital or numerical systems
17	PORTABLE-MOUNTED MOTOR AND/OR		
<i></i>	•		Contouring systems
_,	PORTABLE-MOUNTED ELECTRICAL	570	Contouring systemsWith "feed-rate" control
	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR	570 571	With "feed-rate" control
560	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR POSITIONAL SERVO SYSTEMS (E.G.,	570	With "feed-rate" controlWith "zero-offset" or tool
560	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)	570 571 572	With "feed-rate" controlWith "zero-offset" or tool radius correction
	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS) .Adaptive or optimizing systems	570 571 572 573	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating means
560 561	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos	570 571 572	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point
560	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos Time-sharing or multiplexing	570 571 572 573 574	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systems
560 561 562	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems	570 571 572 573 574	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systems
560 561	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems .With protective or reliability	570 571 572 573 574	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or
560 561 562	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g.,	570 571 572 573 574 575 576	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followers
560 561 562 563	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)	570 571 572 573 574	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsNultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line
560 561 562 563	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems  With protective or reliability increasing features (e.g., "fail-safe" systems) "Redundant" operating channels	570 571 572 573 574 575 576	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followers
560 561 562 563 564 565	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems) "Redundant" operating channelsMonitoring systems	570 571 572 573 574 575 576 577	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followers
560 561 562 563	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems  With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems Maneuver, force, or load-	570 571 572 573 574 575 576 577 578 579	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems
560 561 562 563 564 565 566	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems) "Redundant" operating channelsMonitoring systems Maneuver, force, or load- limiting	570 571 572 573 574 575 576 577	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems .Vehicular guidance systems with
560 561 562 563 564 565	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems  With protective or reliability increasing features (e.g., "fail-safe" systems)  "Redundant" operating channels  Monitoring systems  Maneuver, force, or load- limiting  Program- or pattern-controlled	570 571 572 573 574 575 576 577 578 579 580	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systemsMultiple pass systemsMultiple pass systemsMultiple pass systems
560 561 562 563 564 565 566	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems  .Maneuver, force, or load- limiting .Program- or pattern-controlled systems	570 571 572 573 574 575 576 577 578 579 580	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systemsMultiple pass systems
560 561 562 563 564 565 566	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems Maneuver, force, or load- limiting .Program- or pattern-controlled systems With program recording or	570 571 572 573 574 575 576 577 578 579 580 581 582	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigation
560 561 562 563 564 565 566 567	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems Maneuver, force, or load- limiting .Program- or pattern-controlled systems  .With program recording or composing means	570 571 572 573 574 575 576 577 578 579 580 581 582 583	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systemsMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigationLanding systems
560 561 562 563 564 565 566	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems  With protective or reliability increasing features (e.g., "fail-safe" systems)  "Redundant" operating channels  Monitoring systems  Maneuver, force, or load- limiting  Program- or pattern-controlled systems  With program recording or composing means  Multifunction manipulator	570 571 572 573 574 575 576 577 578 579 580 581 582 583 584	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systemsMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigationLanding systemsAltitude or pitch control
560 561 562 563 564 565 566 567 568.1 568.11	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems Maneuver, force, or load- limiting .Program- or pattern-controlled systems With program recording or composing means Multifunction manipulator (i.e., Robot)	570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigationLanding systemsAltitude or pitch controlRoll control
560 561 562 563 564 565 566 567	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  Adaptive or optimizing systems including "bang-bang" servos  Time-sharing or multiplexing systems  With protective or reliability increasing features (e.g., "fail-safe" systems)  "Redundant" operating channels  Monitoring systems  Maneuver, force, or load- limiting  Program- or pattern-controlled systems  With program recording or composing means  Multifunction manipulator	570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585 586	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigationLanding systemsAltitude or pitch controlRoll controlYaw control
560 561 562 563 564 565 566 567 568.1 568.11	PORTABLE-MOUNTED ELECTRICAL SYSTEMS THEREFOR  POSITIONAL SERVO SYSTEMS (E.G., SERVOMECHANISMS)  .Adaptive or optimizing systems including "bang-bang" servos .Time-sharing or multiplexing systems  .With protective or reliability increasing features (e.g., "fail-safe" systems)  ."Redundant" operating channelsMonitoring systems Maneuver, force, or load- limiting .Program- or pattern-controlled systems With program recording or composing means Multifunction manipulator (i.e., Robot)	570 571 572 573 574 575 576 577 578 579 580 581 582 583 584 585	With "feed-rate" controlWith "zero-offset" or tool radius correctionWith interpolating meansMultiple axes point to point systemsMultiple axes analog systemsNonmechanical line, seam or edge followersOptical or photoelectric line followersCam or template followersMultiple pass systems .Vehicular guidance systems with single axis controlRadio-controlledCelestial navigationLanding systemsAltitude or pitch controlRoll control

588	Marine vehicles	625	.Plural servomotors
589	Submarine and torpedo systems	626	.Limit or end-stop control
590	.Multiple mode systems	627	Secto-scanning systems
591	With mode-engagement features	628	."Feelback" systems
	(e.g., manual to automatic)	629	.Unwanted harmonic or voltage
592	Fine and coarse systems		component elimination
593	Separate fine and coarse		quadrature rejection systems
	motors	630	.Antibacklash systems (e.g., with
594	Digital systems		unidirectional approach to
595	Multiple speed synchro systems		balance)
596	Combined "on-off" and	631	.Antistatic friction features
	proportional control		(e.g., "dither" voltage)
597	Slewing systems	632	.With compensating features
598	With a separate slewing motor	633	"Two-cycle error" compensation
599	.Pulse-width modulated power	634	Temperature compensation
	input to motor (e.g., "duty	635	.With signal-, voltage-, or
	cycle" systems)		current-limiting
600	.Digital or numerical systems	636	."Sampling" systems including
601	Digital comparison		miscellaneous "sampled data"
602	Commutating switch-type		control systems
	encoder	637	.Analog computation
603	Pulse-counting systems	638	.With particular "error-
604	Analogue comparison		detecting" means
605	Synchro or resolver (e.g.,	639	Plural, diverse conditions
	transmitter simulators)	640	Photoelectric or optical-type
606	.Frequency- or phase-modulated		measuring instruments
	systems	641	With particular temperature
607	Frequency comparison		measuring instrument
608	Phase comparison	642	With liquid level measuring
609	."Reset" systems (P.I.)		instruments
610	With rate (P. I. D.) (e.g.,	643	With moisture content or
	reset windup prevention)		wetness measuring instruments
611	.With stabilizing features (e.g.,	644	With flow measuring instruments
	anti-hunting, damping)	645	With fluid pressure measuring
612	Electric braking near balance		instruments
	(e.g., dynamic)	646	With force or weight measuring
613	D.C. in A.C. windings		instruments
614	Friction-braking near balance	647	With magnetic field measuring
	including magnetic or eddy		instruments
	current brakes	648	With inertial, direction or
615	By auxiliary feedback loop		inclination measuring
616	Rate feedback		instrument
617	Variable rate feedback	649	Stable platforms
618	Tachometer feedback	650	With current, voltage or
619	Variable gain bandwidth		electrical power measuring
620	Nonlinear circuits		instruments
621	Lead or lag networks	651	With acceleration measuring
622	A.C. networks		instruments
623	Load stabilization (e.g.,	652	With particular position
-	viscous, magnetic or friction		measuring instruments
	dampers)	653	Magnetic transducers
624	By deadband at null (e.g.,	654	Synchro control transmitter-
	threshold circuits)		transformer systems
		655	With synchro differential

656	Differential transformer	692	.Having induction or "selsyn"
655	systems	600	type transmitter
657	Linear differential transformer	693	.Having impedance-type transmitter
658	"E" type transformer	694	.Having commutated dynamoelectric
659	"Microsyn" type	0,7 -	machine transmitter
660	"Inductosyn" systems	695	.Having commutating switch-type
661	Resolver systems	0,5	transmitter
662		696	OPEN-LOOP STEPPING MOTOR CONTROL
	Variable capacitor systems	090	SYSTEMS
663	Potentiometer systems	2.4	
	including autotransformers and Wheatstone bridges	34	PLURAL, DIVERSE OR DIVERSELY CONTROLLED ELECTRIC MOTORS
664	Minor arc seeking	35	.Motors with diverse motions
665	Continuous rotation,		(e.g., reciprocating and
005	unlimited range		rotary motors)
666	Controlled tap and slidewire	37	.Plural reciprocating or
667	With a bridge in the feedback	57	oscillating motors
007	_	38	.Plural linear-movement motors
	circuit		
668	Recalibrating systems	39	.Work and feed motors (e.g.,
669	Standing wave		indexing)
670	Contact resistance	40	.Motor biased against rotation
671	.With particular motor control	41	.Having electrical synchronizing
	system responsive to the		interconnections
	"actuating signal"	42	Between windings on auxiliary
672	Discontinuous or "on-off"		dynamo-electric machines
	control	43	D.C. or A.C. commutator motors
673	Seeking switch type		with slip rings
674	Wheatstone bridge type	44	Between induction motor
675	wheatstone bridge typeOne transmitter or controller		secondaries
075		45	
686	element follows another	40	.Mechanically coupled in fixed ratio of movement
676	Transmitter or controller	1.0	
	<pre>element returned (e.g., force balance systems)</pre>	46	Motors having unlike operating characteristics
677	With particular servoamplifier	47	Synchronous and nonsynchronous
678	Differential amplifier		motors
679		48	Mechanically coupled in torque
0/9	Diverse types of amplifiers in different stage	10	opposition
600		49	.Motors electrically connected in
680	Magnetic servoamplifiers	47	
681	Solid-state servoamplifiers	Ε0	cascade or tandem
682	Rotating amplifier (e.g., "Ward Leonard" control)	50	With means for effecting other motor interconnections
683	With particular phase	51	.Plural, diverse motor controls
005	discriminator		for different motors
684		52	.Slipping and/or racing control
004	With particular modulator or	32	for electric motors
605	detector (e.g., choppers)	53	.Plural, diverse motor controls
685	"Step-by-step" motors in		•
	closed-loop servos	54	Motor-reversing
686	Reciprocating or oscillating	55	With running-speed control
	motors	56	And braking
687	Linear movement motors	57	And braking
688	Shaded pole motors	58	And acceleration control
689	TORQUING MOTORS	59	Running-speed control
690	SELF-SYNCHRONOUS TYPE OF MOTOR	60	And braking
691	.With means to amplify	61	And acceleration control
	transmitter signals		
	CTANDMITCECT BIGHAID		

62	And automatic starting and/or	92	Control of both armature (or
02	_	92	primary) and field (or
	stopping and/or with time		
63	delay	93	secondary) circuits
	Braking	93	Series-parallel connected
64	Acceleration control	0.4	armature or primary circuits
65	.Motor-reversing	94	Armature or primary circuit
66	.Running-speed control	0.5	control
67	Diverse speeds for different	95	Series-parallel connections
	motors	96	With armature circuit
68	Relative motor speed control		impedance
69	With speed-difference detector	97	Field or secondary circuit
70	Electrical-type detectors		control
71	Voltage and/or current	98	.Load control
	difference detector	99	Fixed ratio of load or current
72	Dynamoelectric machine		division
	detector	100	By field or secondary circuit
73	Synchronously operated		control
	impedance detectors	101	.Starting and/or stopping
74	Synchronously actuated	102	Sequential or successive
	switch detectors		starting and/or stopping
75	Plural switches connected	103	Selective starting and/or
	in series		stopping
76	Differential-gearing detector	104	Armature (or primary) circuit
77	Controlling motor speed in		control
	response to speed of another	105	.Plural, diverse or diversely
	motor		controlled sources of armature
78	Controlling A.C. frequency or		(or primary) supply
, 0	rate of electrical impulses to	106	Diverse sources
	other motor	107	A.C. and D.C.
79	Control of both armature (or	108	Different voltages
, ,	primary) and field (or	109	Different voltages
	secondary) circuits	110	Different frequencies
80	Armature or primary circuit	111	Different frequencies .Series-parallel connected motors
00	control	112	.Parallel connected motors
81	Field secondary circuit	113	.Series connected motors
01	control	_	
82		114	IMPACT, MECHANICAL SHOCK, OR
02	Armature or primary circuit control	115	VIBRATION-PRODUCING MOTORS
0.2	*****	115	MOTOR WITH DIVERSE MOTIONS (E.G.,
83	Series-parallel armature	116	ROTARY AND RECIPROCATING)
0.4	circuit connections	116	NONMAGNETIC MOTOR
84	Field or secondary circuit	117	.Thermoelectric motor
0.5	control	118	MAGNETOSTRICTIVE MOTOR
85	.Synchronizing or phasing control	119	RECIPROCATING OR OSCILLATING
86	.Braking		MOTOR
87	Motor used as braking generator	120	.Stopping after predetermined
	(dynamic braking)		number of reciprocations or
88	Load or current division		cycles (including single
	during braking		cycle)
89	Motor as exciter for another	121	.Having means to produce a
	motor		progressing or traveling motor
90	.Acceleration control		field flux
91	Accelerating motors in	122	.Plural, diverse or diversely
	succession or selectively		controlled motor windings

123	Polyphase or diverse or	149	.With plural, diverse or
	diversely controlled sources of motor supply		diversely controlled generators
104		1 - 0	3
124 125	A.C. and D.C. sourcesUnidirectionally conductive	150	.With flywheel on generator or on motor
	devices in energizing circuit	151	.Control of both the generator
126	.Energizing winding circuit		and the circuit to the motor
	control	152	With motor control
127	Automatic in response to	153	.Control of both the generator
	predetermined position,		and the motor
	movement or condition in or of the motor or driven device	154	Control of excitation (field) circuit of both
128	Noise, sound, vibration,	156	.Plural, diverse or diversely
-	movement or position of motor	130	actuated, generator control
129	By means for producing periodic		means
	electrical pulses in the	157	.Generator speed control
	energizing circuit	158	.Generator field circuit control
130	Electrical oscillation or	159	HAVING ROTOR ELEMENT BIASED
	condenser charging and/or	137	AGAINST ROTATION
	discharging circuits	160	.By resilient biasing means
131	Motor or escapement-controlled		(e.g., spring)
	means	161	WITH FLYWHEEL OR MASSIVE ROTARY
132	By space-discharge or		MEMBER
	unidirectionally conductive	162	CONTROL BY PATTERNS OR OTHER
	devices in energizing circuit	102	PREDETERMINED SCHEDULE MEANS
133	By impedance devices in	163	.Motor running-speed control
	energizing circuit	164	Cyclically varying or repeated
134	By circuit making and/or	101	speed schedules
	braking devices	700	-
135	LINEAR-MOVEMENT MOTORS	700	SYNCHRONOUS MOTOR SYSTEMS
136	AUXILIARY MEANS FOR PRODUCING	701	.Hysteresis or reluctance motor
130	MECHANICAL STARTING OR	=	systems
	ACCELERATING TORQUE	702	.Antihunting or damping
1 2 7	_	703	.Braking
137	.By auxiliary motor	704	.Pole changing motor winding
138	SPACE-DISCHARGE-DEVICE COMMUTATED		circuits
	MOTOR	705	.Synchronization systems
139	BATTERY-FED MOTOR SYSTEMS	706	With armature power removal
140	GENERATOR-FED MOTOR SYSTEMS		upon failure to synchronize or
	HAVING GENERATOR CONTROL		loss of synchronism
141	.Automatic generator control and/	707	Upon failure to resynchronize
	or with time-delay means	708	Responsive to thermal
142	Responsive to diverse	, 00	electrical element in system
	conditions or with time-delay	709	Having different armature
	means	705	voltage prior to synchronism
143	Plural electrical conditions	710	With d.c. field removal
144	Armature or primary current of	711	With electronic control
	motor	/ 1 1	element in system
145	Terminal voltage or counter	712	With field excitation
	e.m.f. of motor		application
146	Speed of motor or driven device	713	Responsive to slip voltage
147	Speed or frequency of generator	-	frequency in d.c. field
	or its drive means		winding
148	.Alternating-current-motor system	714	Responsive to armature current
	<del>-</del>	715	Responsive to armature currentResponsive to rotor speed or
		, 10	rotor driven member
			TOCOL GIIAGII MEMBEL

716	.Field winding circuits	751	Split phase motor with
717	Responsive to a motor condition		capacitor interchangeably
718	Induced voltage in field		connected in series with
	winding		either primary winding
719	Speed responsive field power	752	With controlled electronic
	sources		device to provide the series
720	.Armature winding circuits		connection
721	Responsive to rotor shaft	753	With de-energizable start
,	position or speed		winding
722	Having electronic power	754	With separate winding or
722	conversion circuit		winding portion energized for
723	Having variable frequency		each direction of rotation
723	supply	755	Automatic current reversal on
724	Having a plurality of windings		start winding
/ 4 4	or winding portions	756	With controlled electronic
725	REPULSION MOTOR SYSTEMS		switch for phase reversal
725 726	.With added motor winding or	757	.Braking
120	3	758	With diverse operation
<b>505</b>	convertible to series motor	759	Dynamic braking
727	INDUCTION MOTOR SYSTEMS	760	_
728	.Repulsion start	700	Direct current primary winding braking circuit
729	.Power-factor control	761	_
730	.With plural separately movable	/ O T	Rotating rotor controls
	rotors		braking current in primary
731	.With voltage source connected to	E.C.O.	winding
	motor secondary	762	With a.c. to d.c. conversion
732	Electronic device controls	E.C.2	circuit
	current in secondary circuit	763	Reversal of power to primary
733	Commutator connected to		winding
	secondary winding	764	Three phase power reversal
734	Slip rings connected to	765	Eddy current braking circuits
	secondary winding	766	.Primary and secondary circuits
735	Rotor shaft coupled to	767	.Primary circuit control
	dynamoelectric machine	768	Three phase motor operated from
736	Slip rings connected to		single phase source
	dynamoelectric machine winding	769	With dynamoelectric converter
737	.Self-cascaded motor windings	770	Dual voltage motors
738	.With commutated winding	771	Delta-wye, plural wye, or
739	.Reversing		plural delta connected primary
740	With diverse motor operation		windings
741	With braking	772	Plural speed
742	Electromagnetic brakes	773	Pole changing
743	Generator action	774	Single phase motor
744	Plugging	775	Separate primary running
745	With controlled saturable		winding for each pole number,
743			alternately energized
746	reactor in primary circuit	776	Entire primary running
	Two phase motor		winding energized for each
747	Two phase motor		running speed
748	With plural primary windings	777	Separate primary running
	or winding portions having		winding for each pole number,
740	common connection		alternately energized
749	Operating from a single phase	778	Starting control
750	source	779	With speed control
750	Shaded pole motor	-	

780			
, 00	Three phase motor with	809	With voltage phase angle
	variable transformer to		control
	initially adjust voltage to motor windings	810	With voltage pulse time control
781	Operating from a single phase source	811	Pluse width modulation or chopping
782	With protective features	010	
783	_	812	Voltage control
703	Thermal starting and thermal	813	With transformer
E0.4	overload protection	814	With impedance control
784	Impedance for reducing	815	Saturable reactor
	current during starting operation	816	Single phase, split phase motors
785	Start winding removed during	817	With capacitor
	running operation	818	.Secondary circuit control
786	By electronic switch	819	Open secondary member or
787	With transformer for	019	<del>-</del>
707	sensing the run winding		portion thereof with means to
	current		open or close the circuit thereto
788	With variable temperature	820	Closed secondary member or
	coefficient resistor in switch		member portion with means to
	control circuit		change electrical
789	By electromagnetic switch		characteristics thereof
790	With relay coil in series	821	Impedance control of secondary
	with main winding	021	circuit
791	By thermal switch	822	Responsive to motor condition
792	With variable temperature	823	Rotor speed or position
	coefficient impedance element		responsive
793	By centrifugal switch	824	Centrifugal force of rotor
794	Capacitor run motor with different capacitance at		<pre>controls secondary circuit impedance</pre>
	starting	825	Induction motor current
795	With plural capacitors	023	Induction motor current
1 ) )		026	Desimones makes assessed
706		826	Primary motor current
796	Saturable winding in capacitor run motor circuit	826 827	<pre>Primary motor currentFrequency of secondary current</pre>
796 797	Saturable winding in		Frequency of secondary current
	Saturable winding in capacitor run motor circuit	827	Frequency of secondary currentSecondary voltage
	<ul><li>Saturable winding in capacitor run motor circuit</li><li>Phase splitting using stator</li></ul>	827 828 829	<ul><li>Frequency of secondary current</li><li>Secondary voltage</li><li>By manual operation</li></ul>
	<ul><li>Saturable winding in capacitor run motor circuit</li><li>Phase splitting using stator winding mutual inductance or</li></ul>	827 828	<ul><li>Frequency of secondary current</li><li>Secondary voltage</li><li>By manual operation</li><li>.With relatively movable</li></ul>
797 798	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor condition	827 828 829	<ul><li>Frequency of secondary current</li><li>Secondary voltage</li><li>By manual operation</li><li>.With relatively movable cooperating motor parts to</li></ul>
797	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or	827 828 829 830	<ul> <li>Frequency of secondary current</li> <li>Secondary voltage</li> <li>By manual operation</li> <li>.With relatively movable cooperating motor parts to control energized motor</li> </ul>
797 798 799	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angle	827 828 829	<pre>Frequency of secondary     currentSecondary voltageBy manual operation .With relatively movable     cooperating motor parts to     control energized motorAxially movable cooperating</pre>
797 798	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power	827 828 829 830	<pre>Frequency of secondary     currentSecondary voltageBy manual operation .With relatively movable     cooperating motor parts to     control energized motorAxially movable cooperating     parts</pre>
797 798 799 800	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversion	827 828 829 830	<pre>current current c</pre>
797 798 799 800 801	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverter	827 828 829 830 831 832	<pre>current currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable</pre>
797 798 799 800	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversion	827 828 829 830	<pre>current current c</pre>
797 798 799 800 801	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional	827 828 829 830 831 832	<pre>current currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING</pre>
797 798 799 800 801 802	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional condition	827 828 829 830 831 832 244 245	<pre>current currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS</pre>
797 798 799 800 801 802	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to	827 828 829 830 831 832 244 245 246	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS
797 798 799 800 801 802	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter	827 828 829 830 831 832 244 245	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motor .Axially movable cooperating parts .Dual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor
797 798 799 800 801 802 803	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supply	827 828 829 830 831 832 244 245 246 247	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation
797 798 799 800 801 802 803	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic	827 828 829 830 831 832 244 245 246	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motorAxially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or
797 798 799 800 801 802 803	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactance	827 828 829 830 831 832 244 245 246 247	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motor .Axially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or
797 798 799 800 801 802 803 804 805	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactanceResponsive to motor voltageCondition responsive	827 828 829 830 831 832 244 245 246 247 248	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motor .Axially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or controlled sources of e.m.f.
797 798 799 800 801 802 803 804 805 806	Saturable winding in capacitor run motor circuitPhase splitting using stator winding mutual inductance or saturable windingResponsive to motor conditionResponsive to speed or rotation phase angleWith controlled power conversionIncluding inverterResponsive to an additional conditionWith controlled a.c. to d.c. circuit in inverter supplyWith controlled magnetic reactanceResponsive to motor voltage	827 828 829 830 831 832 244 245 246 247	currentSecondary voltageBy manual operation .With relatively movable cooperating motor parts to control energized motor .Axially movable cooperating partsDual stators, one or both angularly movable  ALTERNATING CURRENT COMMUTATING MOTORS .Universal or A.CD.C. motors SERIES MOTORS .Convertible for nonseries motor operation .With plural, diverse or diversely connected or

250	Impedance in series with field windings and in parallel to armature winding	284	With means to delay reversing until motor substantially stops
251	.Field circuit control	285	Instant of, or passage or
252	Plural, diverse or diversely connected or controlled field		<pre>predetermined time or having time-delay means</pre>
	coils	286	Movement or position of motor
253	HOMOPOLAR OR UNIFORM FIELD MOTORS		or driven device
254	SELF-COMMUTATED IMPULSE OR	287	.Armature or primary circuit
	RELUCTANCE MOTORS	000	control
255	PLURAL DIVERSE MOTOR CONTROLS	288	Plural, diverse or diversely
256	.Motor-reversing	200	controlled armature windings
257	With running-speed control	289	Phase-reversal
258	And braking	290	Selectively energized windings
259	And acceleration control	291	Armature or primary current
260	And acceleration control		reversal
261	With braking	292	By shifting motor brushes or
262	And acceleration control		selecting appropriate set of
263	With acceleration control		brushes
264	With automatic starting and/or stopping	293	Reversing polarity of current supplied to armature circuit
265	Stopping upon predetermined	294	Wheatstone bridge type
	movement of or position of	295	Potentiometer-controlled
	motor or driven device	296	.Field circuit control
266	At limit-of-travel of motor	297	Plural, diverse or diversely
	or driven device		controlled field windings
267	Dual control circuits	298	Simultaneous energization
	alternately energized	299	With means for short-
268	.Running-speed control		circuiting a winding
269	With braking	300	Field-circuit current reversed
270	And acceleration control		
271	With acceleration control	Class 38	8 subclasses 800-841 are an inte-
272	With automatic starting and/or stopping	shown by	t of this Class (Class 318), as the position of this box, and
273	.Motor braking		the schedule hierarchy of this
274	With acceleration control		etaining all pertinent definitions
275	With automatic starting and/or	and Clas	s lines of this class.
_ , 0	stopping		
276	.Acceleration control		
277	With automatic starting and/or		
2,,	stopping	362	BRAKING
278	In response to an electrical condition	363	."Spotting" or adjustment of braking controller during
279	Automatic stopping means less		coasting
	responsive during acceleration	364	.Automatic and/or with time-delay means
280	MOTOR-REVERSING	365	Plural diverse conditions or
281	.Periodic- or intermittent- reversing		with time delay
282	In response to movement or	366	Condition of motor or driven
	position (e.g., limit of	265	device
	travel) of motor or driven	367	Armature or primary current
	device	368	Armature or primary circuit
283	.Automatic and/or with time-delay means		<pre>voltage or terminal or counter e.m.f. voltage</pre>

369	Speed, acceleration, movement	438	POWER FACTOR CONTROL OF ARMATURE
	or position of motor or driven		OR LINE CIRCUIT
	device	439	MOTOR COMMUTATION CONTROL SYSTEMS
370	.Plural, diverse or diversely	440	HAVING PLURAL, DIVERSE OR
	controlled braking means		DIVERSELY CONTROLLED SOURCES
371	Including both friction braking	441	.A.C. and D.C.
	"plugging" and/or dynamic	442	.Different voltages
	braking	443	PERIODIC, REPETITIOUS OR
372	.Friction braking		SUCCESSIVE OPERATIONS CONTROL
373	."Plugging" or application of		OF MOTOR, INCLUDING "JOG" AND
	reverse power to motor		"INCH" CONTROL
374	Energy flow interrupted when	444	.Variable periods or intervals
	motor stops		between controlling operations
375	.Dynamic braking	445	AUTOMATIC AND/OR WITH TIME-DELAY
376	Regenerative		MEANS (E.G., AUTOMATIC
377	With additional source of		STARTING AND/OR STOPPING)
	e.m.f.	446	.With nonautomatic control means
378	In series with armature or		(e.g., manual)
	primary circuit	447	.Nonresponsive or less responsive
379	Locally closed armature circuit		for limited periods
380	Closed through impedance or	448	.Anti-hunting
300	the like	449	.With respect to a fixed
381	With field or secondary	117	standard, master or reference
301	circuit control		device
382	.By auxiliary electric generator	450	Electrical detector
302	or by magnetic attraction or	451	Mechanically vibrating device
		431	as reference device (e.g.,
383	repulsion devices		tuning fork)
383	"ANTI-BRAKING" OR BRAKING-	452	.Plural, diverse conditions or
	PREVENTION MEANS	432	with time-delay means
	38 subclasses 842-860 are an inte-	453	Electrical condition
	ct of this Class (Class 318), as	454	Plural, diverse electrical
	y the position of this box, and		conditions
	the schedule hierarchy of this	455	Voltage and current (e.g.,
	retaining all pertinent definitions		watts)
and Clas	ss lines of this class.	456	.Rate-of-change of a condition
		457	Interia-type detector
		458	Electrical condition
		459	.Terminal voltage or counter-
430	MOTOR LOAD, ARMATURE CURRENT OR		electromotive force of
	FORCE CONTROL DURING STARTING		controlled motor
	AND/OR STOPPING	460	.Sound, supersonic vibration or
431	.Initial, "cracking" or "starting		mechanical vibration
	from rest" torque control	461	.Speed or rate-of-movement
432	CONSTANT MOTOR CURRENT, LOAD AND/	462	Centrifugal-type detector
	OR TORQUE CONTROL	463	Tachometer-type detector
433	.Control of motor load or device	464	Electric generator tachometer
	driven	465	In excess of a predetermined
434	LIMITATION OF MOTOR LOAD,	TOD	valve
	CURRENT, TORQUE OR FORCE	100	
	(E.G., PREVENTING OVERLOAD)	466	.Movement, position, or limit-of-
436	NONRUNNING, ENERGIZED MOTOR	167	travel
437	PHASING OR ANGULAR OR LINEAR	467	Plural sensing means for
	POSITIONAL CONTROL OF MOVABLE		determining plural positions
	ELEMENT OF THE MOTOR	160	or plural limits-of travel
		468	Limit-of-travel control means

469	<pre>Overloading limit-of-travel- type control means</pre>	500	<pre>.Plural sources of voltage   (including counter e.m.f.</pre>
470	Magnitude of movement or revolutions	501	cells) .By shunting armature or primary
471	Responsive to thermal conditions	301	winding armature or primary
472	Of motor control means	502	.Variable length or tapped
472		302	armature winding
4/3	In or about the motor being	503	
474	controlled	503	.Frequency or pulsation control
474	.Motor load, armature or primary		.Voltage control
4	or secondary circuit current	505	.By means to space-discharge
475	Mechanical-type detector (e.g.,	506	devices
	by yielding spring devices)	506	Plural, diverse or diversely
476	In excess of a predetermined		connected or controlled space-
	magnitude	<b>505</b>	discharge devices
477	Intentionally increased load	507	Having discharge-control means
478	.Electrical conditions in circuit	<b>500</b>	(e.g., grids)
	other than controlled motor	508	.Impedance-controlled
	circuit	509	Plural, diverse or diversely
479	Voltage		controlled impedances
480	.Radiant energy	510	Including both reactor and
481	.Pressure in a fluid or granular		condenser
	material	511	Inherently or self-variable
482	.Level of fluid or granular		impedance
	material	512	Inductive reactor controlled
483	.Moisture content or wetness	513	Having auxiliary means for
484	.Time or with time-delay means		saturating reactor core
485	Dash-pot or other mechanical	514	Resistor-controlled
	delay means	515	Having short-circuiting means
486	Pilot- or servo-motors	516	Short-circuited step-by-step
487	Electromagnetic or inductive	519	.By armature or primary circuit-
	time-delay means		making and/or breaking
488	.Responsive to stress in body or	520	Electromagnetically actuated
	material	521	FIELD OR SECONDARY CIRCUIT
489	.Responsive to direction,		CONTROL
	inclination or angular	523	.Plural, diverse or diversely
	position of bodies		connected or controlled field
490	WITH SIGNALS, METERS, RECORDERS		windings
	OR TESTING DEVICES	524	Convertible number-of-poles
491	CONTROL OF BOTH MOTOR CIRCUIT AND		type (e.g., 4-pole or 6-pole)
	MOTOR STRUCTURE	525	Differentially wound or
492	MOTOR MAGNETIC ENERGY DISSIPATION		energized windings
493	CONTROL OF BOTH ARMATURE (OR	526	Series-parallel
	PRIMARY) CIRCUIT AND FIELD (OR	527	Series field winding
	SECONDARY) CIRCUIT	528	With means to short circuit a
494	ARMATURE (OR PRIMARY) CIRCUIT		field winding
	CONTROL	529	Selectively energized
495	.Plural, diverse or diversely	530	.Plural, diverse or diversely
	controlled, armature or		connected or controlled
	primary windings		sources of field circuit
496	Polyphase windings		voltage
497	Series-parallel	531	.Variable length or tapped field
498	Energized or controlled in		winding
			_
	predetermined sequence	532	.By means of space-discharge
499	<pre>predetermined sequenceWound or energized in magnetic</pre>		.By means of space-discharge device in field circuit
499	predetermined sequence	532 533	.By means of space-discharge

534	Plural, diverse or diversely
	connected or controlled field
	circuit impedances
535	Wheatstone bridge
536	.By field circuit making and/or
	breaking
537	Intermittently operated
538	MOTOR STRUCTURE ADJUSTMENT OR
	CONTROL
539	.Both armature and field
	structures rotatable or
	adjustable
540	.Rotor element movable axially
541	.Brush or other current-collector
	control
542	Having movement toward or from
	cooperating part (e.g., brush
	lifted from commutator)
543	THREE-OR-MORE-POSITIONS MOTOR
	CONTROLLER SYSTEMS
544	.With other motor control device
545	Main line switch
546	.Plural, diverse or diversely
	controlled controllers
547	Plural control stations
548	.Plural control stations
549	.Return to "off", "starting" or
	"neutral" positions
550	Power-operated controllers
551	.Knee- or foot-operated
	controllers
552	.Power-actuated controllers
553	Separately actuated controller
	contacts
554	Electromagnetic actuated
555	Electromagnetic actuated
556	Reciprocating or oscillating
	electromagnetic means
557	Intermittent or step-by-step
	operation
558	MISCELLANEOUS
555	

## FOREIGN ART COLLECTIONS

FOR 000 CLASS-RELATED FOREIGN DOCUMENTS

## <u>DIGESTS</u>

## DIG 2 WINDSHIELD WIPER CONTROLS